Improvement of RF Operation at KURRI FFAG

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PURPOSE OF THIS TALK

is to clarify how the rf is operated and and what is the possible improvement in the future.

CONTENTS

- 1. How to make rf pattern
 - constant amplitude, constant acc phase
 - AM function is experimentally determined
- 2. Variable k-index
- 3. Future improvement (briefly)

HOW TO DETERMINE THE PATTERN

$$V(t) = V_0(t)\sin\Psi(t)$$

Requirements for V(t) and $\Psi(t)$

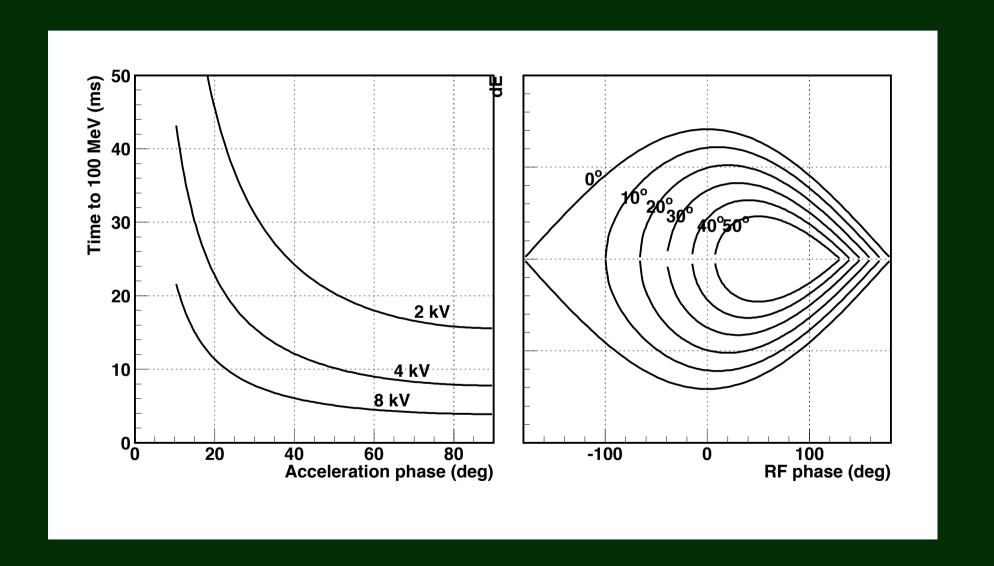
- 1. V(t) < Vmax , by the power of amplifier
- 2. $\phi_s \simeq const.$, or changes very slowly
- 3. bucket area is wide (high V, low $\overline{\phi}$ s) Acceleration is fast (high V, high ϕ s)

Our choice

- 1. Constant, highest Vo (=4kV)
- 2. Constant ϕ s, (no flatbase, no flattop!)

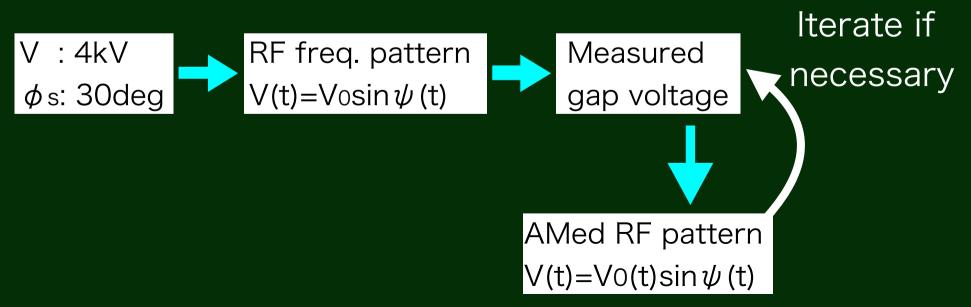
 The value is experimentally determined, such that the accelerated beam intensity takes maximum.

cf. ACCELERATION TIME, BUCKET AREA



RF PATTERN EDIT

- 1. Assume constant amplitude and accelerating phase.
- 2. Derive rf pattern ψ (t)=...
- 3. Apply rf pattern to the amplifier
- 4. Measure the gap voltage amplitude, which is affected by cavity impedance
- 5. AM correction on low level rf.



PATTERN 1

This assumption was CONSTANT K \longrightarrow not true (later) CONSTANT V0 and ϕ s

until Jan. 16, 2014

RF WAVEFORM

RF waveform is analytically expressed in function of time, if energy gain per turn is constant $V\sin\phi_s = \Delta E$

Scaling rule
$$\frac{B}{B_0} = \left(\frac{r}{r_0}\right)^k \longrightarrow \frac{r}{r_0} = \left(\frac{p}{p_0}\right)^{\alpha}, \quad \alpha = \frac{1}{k+1}$$

$$\longrightarrow \frac{f}{f_0} = \left(\frac{p}{p_0}\right)^{1-\alpha} \frac{E_0}{E}$$

Thus

$$\frac{dE}{dt} = fV_0 \sin \phi_s = f_0 \Delta E \left(\frac{p}{p_0}\right)^{1-\alpha} \frac{E_0}{E}$$

$$p(t) = p_0 \left[(1+\alpha) \frac{E_0 \Delta E}{p_0^2} f_0 \cdot t + 1 \right]^{\frac{1}{1+\alpha}} \qquad \Psi(t) = 2\pi \frac{E(t) - E_0}{\Delta E}$$

$$\Psi(t) = 2\pi \frac{E(t) - E_0}{\Delta E}$$

where reference parameters, po, fo, are evaluated at t=0

PROGRAMMED WAVEFORM

$$V(t) = \frac{1}{C_{AM}(t)} \text{sin}\left(\sqrt{A_1 + A_2(t + A_3)^B} - A_4\right) \qquad T_{acc} = \frac{1}{C}\left[\left(\frac{p_f}{p_i}\right)^B - 1\right]$$

$$T_{\mathtt{acc}} = rac{1}{\mathtt{C}} \left[\left(rac{\mathtt{p_f}}{\mathtt{p_i}}
ight)^{\mathtt{B}} - 1
ight]$$

$$\mathtt{A_1} = \left(rac{2\pi\mathtt{m}}{\mathtt{\Delta}\mathtt{E}}
ight)^2$$

$$\mathtt{A_3} = \mathtt{1/C} - \delta\mathtt{t}$$

$$\Delta E = V_0 {
m sin} \phi_{
m s}$$

$$\mathtt{A}_2 = \left(rac{2\pi \mathtt{p}_0}{\Delta\mathtt{E}}
ight)^2 \mathtt{C}^\mathtt{B}$$

$$egin{align} \mathtt{A}_1 &= \left(rac{2\pi\mathtt{m}}{\Delta\mathtt{E}}
ight)^2 & \mathtt{A}_3 &= 1/\mathtt{C} - \delta\mathtt{t} \ & \mathtt{A}_2 &= \left(rac{2\pi\mathtt{p}_0}{\Delta\mathtt{E}}
ight)^2\mathtt{c}^\mathtt{B} & \mathtt{B} &= rac{2}{1+lpha} &= rac{2\mathtt{k}+2}{\mathtt{k}+2} \ & \mathtt{B} &= rac{2}{1+lpha} &= rac{2\mathtt{k}+2}{\mathtt{k}+2} \ & \mathtt{B} &= \mathbb{A} &= \mathbb{A}$$

$$C = (1 + \alpha) \frac{f_0 E_0 \Delta E}{p_0^2}$$

 E_0 Injection energy

Revolution frequency at E_0

k Field index

 ΔE Energy gain per turn

 C_{AM} Amplitude modulation

 δt Time offset (energy redundancy) m+11 MeV

-> next slide

-> next slide

 $4kV \times \sin \phi s$

-> later

~0.5ms, later

REFERENCE PARAMETERS

May 2008

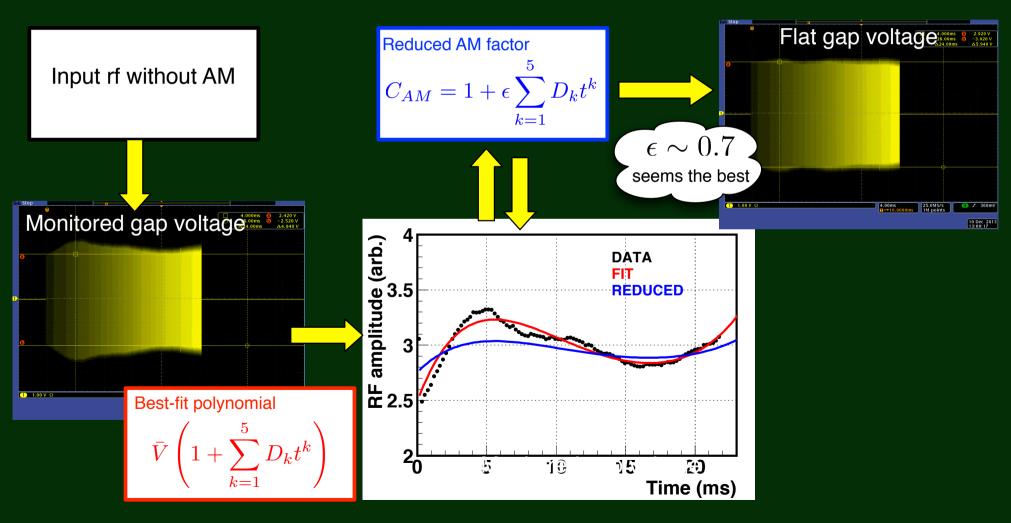
A set of measured (E,f) determined reference f0
 f = 1591.84 kHz for Ek = 11.57MeV
 measured with injected beam from the booster FFAG.
 k-index was assumed to be 7.5 (designed value)

Jul 2008

2. Another set of measured (E,f) modified k-value r = 5039.5 mm (straight section) for f = 3841.7 kHz (assumed 100 MeV) ---> k = 7.645

AMPLITUDE CORRECTION

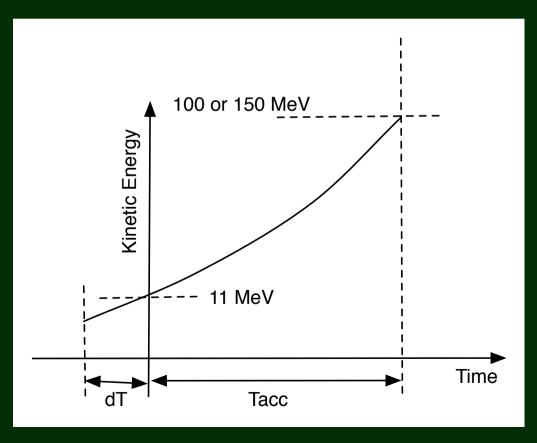
How the amplitude function CAM was determined



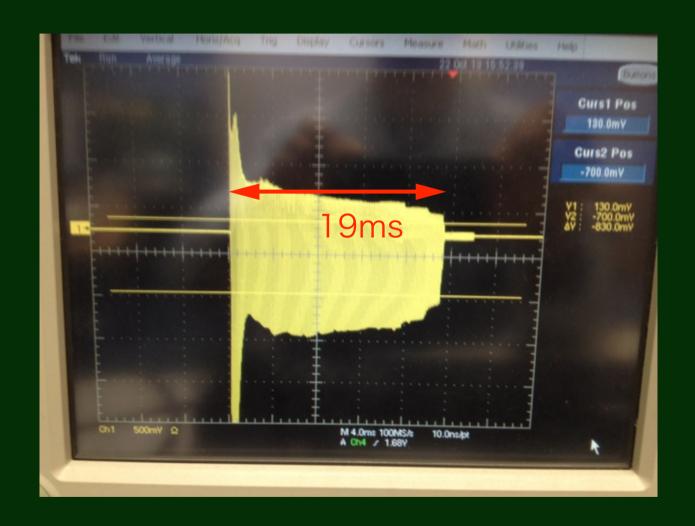
TIME OFFSET

The rf pattern starts below the injection energy, to have energy-redundancy.

Everyday before operating, RF trigger delay, relative to the ion-source, is optimized with monitoring captured intensity.



ACCELERATED BEAM INTENSITY



Fast loss at very beginning of the acceleration.

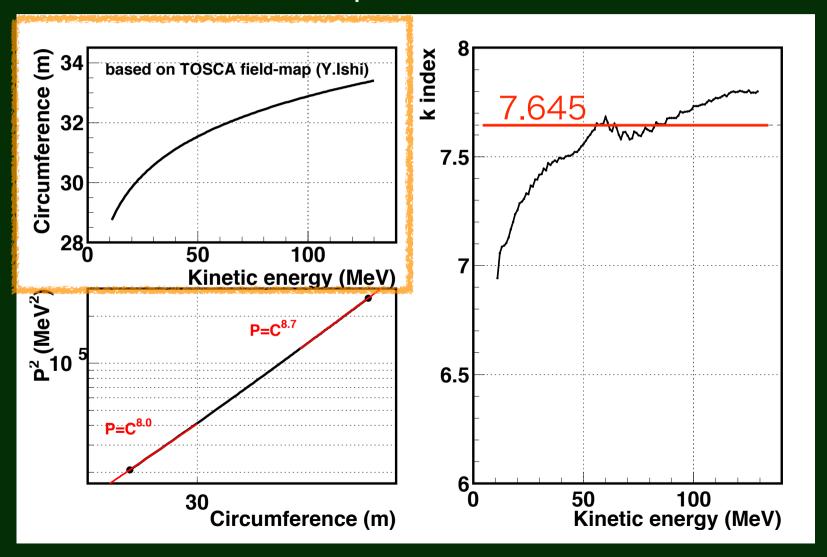
PATTERN 2

SIMULATED VARIABLE K CONSTANT Vo and ϕ s

since Jan. 16, 2014

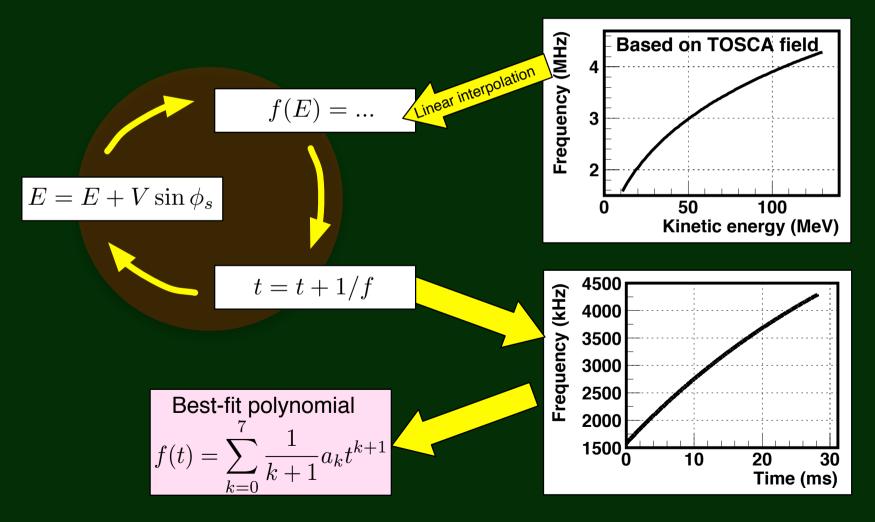
SIMULATED K

According to simulation based on TOSCA field-map, k-index is not constant.



PROGRAMED WAVEFORM

$$V(t) = rac{1}{C_{AM}} sin \left(2\pi \sum_{7}^{k=1} a_k (t - \delta t)^k
ight)$$

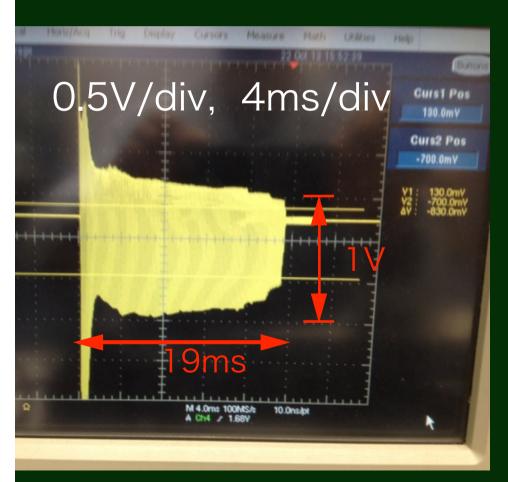


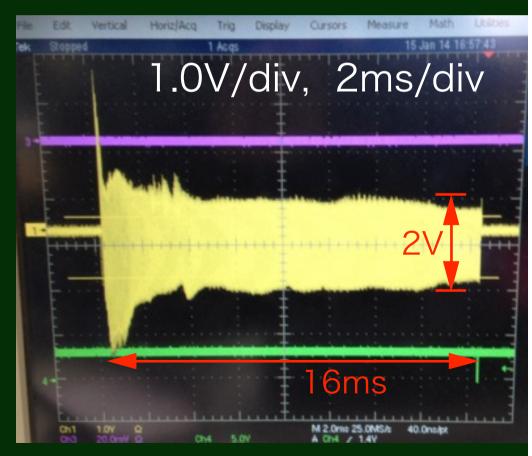
RESULTS

constant k

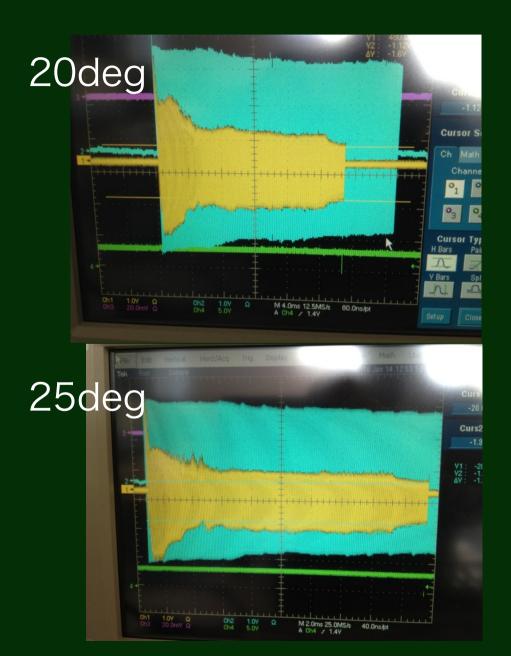


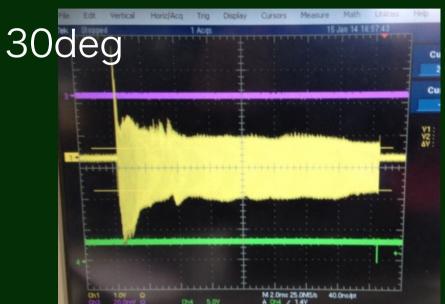
variable k

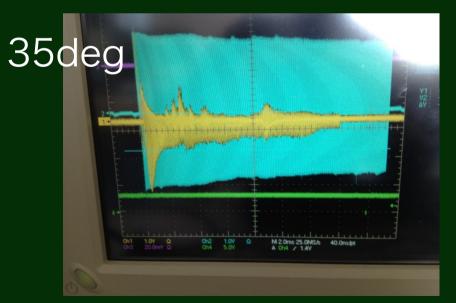




BEST ϕ s IS 20deg?

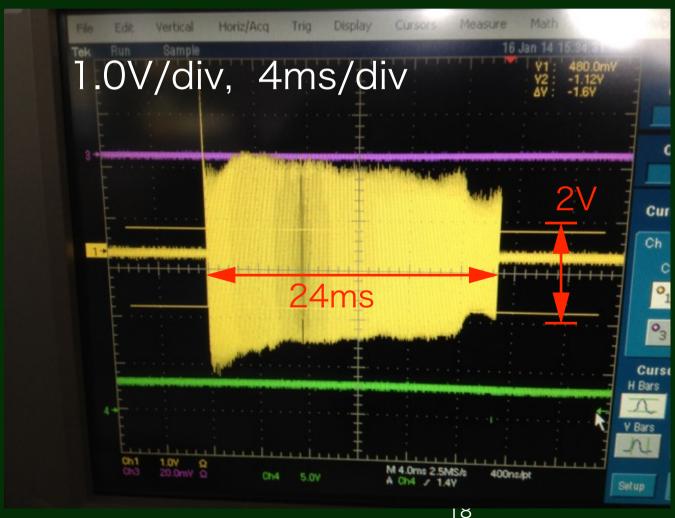






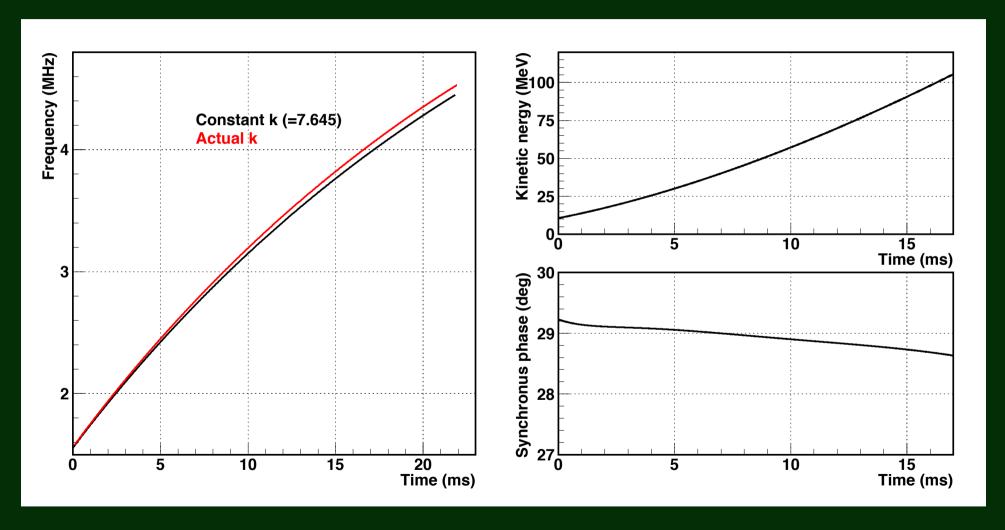
BEST

(After optimizing injection angle etc.) Fast beam loss disappeared and beam intensity became twice!



FREQUENCY DIFFERENCE

Pattern 1 (constant k) on simulated k



Variation of ϕ s is only 1 deg?

WHY PATTERN2 IMPROVED?

FURTHER IMPROVEMENT

ADDITIONAL RF CAVITY

will be installed on Jan. 2015.

With this cavity, the rf voltage is becomes twice? and thus

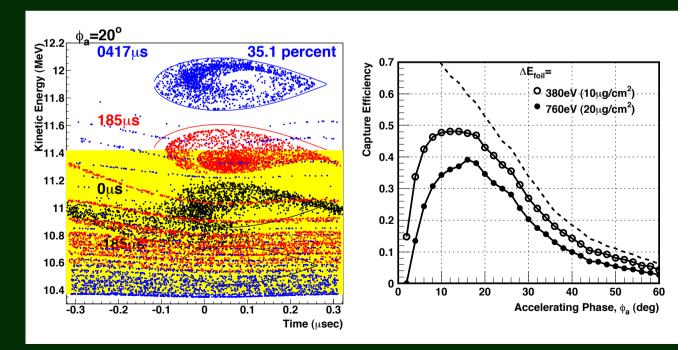


- (1) fast acceleration for
 - (1A) higher repetition, and/or
 - (1B) larger turn separation at inj.
- (2) wide (stable) bucket area
- (3) Suppress harmonic field components excited by rf cavity.

MODIFICATION OF V OR ϕ s

RF amplitude and/or synchronous phase is not necessarily constant, but can be changed with energy. for example,

- (1) Higher V and lower ϕ s only in the injection energy region, where the beam is affected the energy loss at the charge stripping foil
- (2) V decreased along with the beam energy, to keep bucket area? (V proportional to 1/sqrt(E))



SUMMARY

In the KURRI FFAG, the rf is operated very simply in constant V and ϕ s. No flat base nor flat top is made. By considering the variable k-index, which is obtained by TOSCA-based simulation, the beam intensity has been increased by more than twice.

Future improvement will be done by

- (1) Install additional cavity
- (2) Introducing more sophisticated pattern